

**INFORMATION DISCLOSURE
STATEMENT BY APPLICANT****Complete if Known**

Application No.	10/642,477
Filing Date	August 15, 2003
First Named Inventor	Masakazu Kawai
Art Unit	3736
Examiner Name	Jeffrey Gerben Hoekstra
Attorney Docket Number	20911-08172

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U.S. PATENT DOCUMENTS

U.S. PATENT DOCUMENTS				
Examiner Initials*	Cite No. ¹	Document No. Number – Kind Code ² (if known)	Date MM-DD-YYYY	Name of Patentee or Applicant of Cited Document
	A1	US-7,260,450	08-21-2007	Okazaki et al.
	A2	US-7,191,036	03-13-2007	Takenaka et al.
	A3	US-7,184,858	02-27-2007	Okazaki et al.
	A4	US-7,024,279	04-04-2006	Rose III et al.
	A5	US-7,010,390	03-07-2006	Graf et al.

FOREIGN PATENT DOCUMENTS

FOREIGN PATENT DOCUMENTS					
Examiner Initials*	Cite No. ¹	Foreign Patent Document Country Code ³ – Number ⁴ Kind Code ⁵ (if known)	Publication Date MM-DD-YYYY	Name of Patentee or Applicant of Cited Document	T ⁶

OTHER REFERENCES – NON-PATENT LITERATURE DOCUMENTS

Examiner Initials*	Cite No. ¹	Include name of the author (in CAPITAL LETTERS), title of the article (when appropriate), title of the item (book, magazine, journal, serial, symposium, catalog, etc.), date, page(s), volume-issue number(s), publisher, city and/or country where published	T ⁶
	C1	ASENSIO, J.R. et al., "Kinematic and Dynamic Model-Based Motion Controller for Mobile Robots," IFAC, 2002, 6 pages.	
	C2	PCT International Search Report and Written Opinion, PCT/US06/01116, January 17, 2008, 12 pages.	
	C3	WU, G. et al., "The Study of Kinematic Transient in Locomotion Using the Integrated Kinematic Sensor," IEEE, 1996, pp. 193-200.	

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*EXAMINER: Initial if reference considered, whether or not citation is in conformance with MPEP 609.

Draw line through citation if not in conformance and not considered. Include copy of this form with next communication to applicant.

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